

# VECTOR CALCULUS

1

## *Divergence*

$$\operatorname{div} \vec{A} = \nabla \cdot \vec{A} = \lim_{\Delta v \rightarrow 0} \frac{\oint_S \vec{A} \cdot d\vec{S}}{\Delta v}$$

$$\oint_S \vec{A} \cdot d\vec{S} = \int_v \nabla \cdot \vec{A} dv$$

$\nabla \cdot \vec{A}$ :

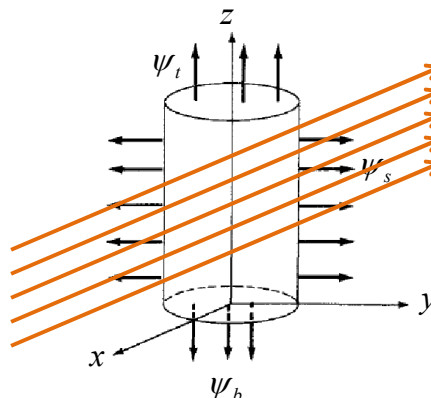
Commonly misinterpreted as the dot product of  $\nabla$  and  $\vec{A}$ .

2

## Example

$$\rho = 1, 0 \leq z \leq 1$$

$$\vec{G} = 10e^{-2z} (\rho \hat{a}_\rho + \hat{a}_z)$$



- Determine the flux of  $\vec{G}$  out of the entire surface of the cylinder.
- Confirm the result using the divergence theorem.

3

## Example

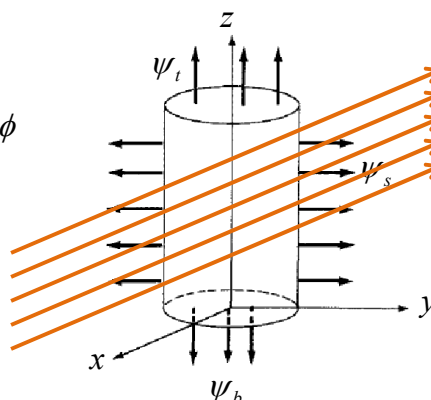
$$\psi = \oint G \cdot d\vec{S} = \psi_t + \psi_b + \psi_s$$

$$\begin{aligned} \psi_t &= \int \vec{G} \cdot d\vec{S} = \int_{\rho=0}^1 \int_{\phi=0}^{2\pi} 10e^{-2} \rho \, d\rho \, d\phi \\ &= 10e^{-2} (2\pi) \rho^2 / 2 \Big|_0^1 = 10\pi e^{-2} \end{aligned}$$

$$\begin{aligned} \psi_b &= \int \vec{G} \cdot d\vec{S} = \int_{\rho=0}^1 \int_{\phi=0}^{2\pi} 10e^0 \rho \, d\rho \, d\phi \\ &= 10(2\pi) \rho^2 / 2 \Big|_0^1 = -10\pi \end{aligned}$$

$$\psi_s = \int \vec{G} \cdot d\vec{S} = \int_{z=0}^1 \int_{\phi=0}^{2\pi} 10e^{-2z} \rho^2 \, dz \, d\phi = 10(2\pi) \frac{e^{-2z}}{-2} \Big|_0^1 = 10\pi(1 - e^{-2})$$

$$\psi = \psi_t + \psi_b + \psi_s = 10\pi e^{-2} - 10\pi + 10\pi(1 - e^{-2}) = 0$$



4

## Example

Using divergence theorem:

$$\psi = \oint_S \vec{G} \cdot d\vec{S} = \int_V (\nabla \cdot \vec{G}) dv$$

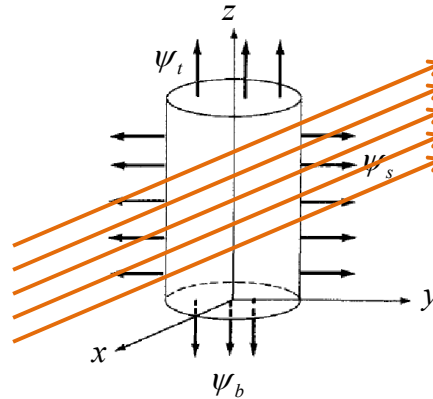
$$\nabla \cdot \vec{G}$$

$$= \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho G_\rho) + \frac{1}{\rho} \frac{\partial}{\partial \phi} G_\phi + \frac{\partial}{\partial z} G_z$$

$$= \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho^2 10e^{-2z}) + \frac{\partial}{\partial z} (10e^{-2z})$$

$$= 20e^{-2z} - 20e^{-2z}$$

$$= 0$$

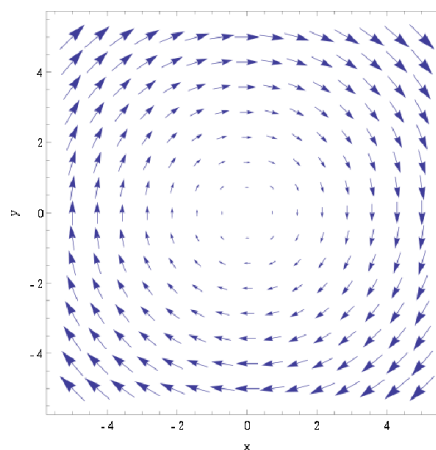


5

## Curl of a Vector

$$\text{curl } \vec{A} = \nabla \times \vec{A}$$

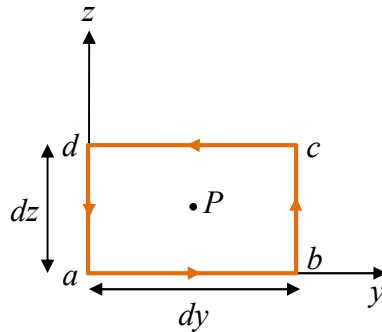
$$= \left( \lim_{\Delta S \rightarrow 0} \frac{\oint_L \vec{A} \cdot d\vec{l}}{\Delta S} \right) \hat{a}_n$$



6

## Curl of a Vector

$$\oint_L \vec{A} \cdot d\vec{l} = \left( \int_{ab} + \int_{bc} + \int_{cd} + \int_{da} \right) \vec{A} \cdot d\vec{l}$$



7

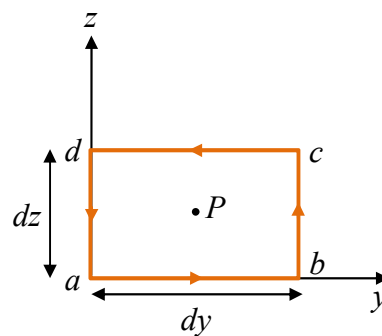
## Curl of a Vector

On side  $ab$ ,  $d\vec{l} = dy \hat{a}_y$  and  $z = z_0 - dz / 2$

$$\oint_{ab} \vec{A} \cdot d\vec{l} = dy \left[ A_y(x_0, y_0, z_0) - \frac{dz}{2} \frac{\partial A_y}{\partial z} \Big|_P \right]$$

On side  $bc$ ,  $d\vec{l} = dz \hat{a}_z$  and  $y = y_0 + dy / 2$

$$\oint_{bc} \vec{A} \cdot d\vec{l} = dz \left[ A_z(x_0, y_0, z_0) + \frac{dy}{2} \frac{\partial A_z}{\partial y} \Big|_P \right]$$



Similarly,

$$\oint_{cd} \vec{A} \cdot d\vec{l} = -dy \left[ A_y(x_0, y_0, z_0) + \frac{dz}{2} \frac{\partial A_y}{\partial z} \Big|_P \right]$$

$$\oint_{da} \vec{A} \cdot d\vec{l} = -dz \left[ A_z(x_0, y_0, z_0) - \frac{dy}{2} \frac{\partial A_z}{\partial y} \Big|_P \right]$$

$$\lim_{\Delta S \rightarrow 0} \oint_L \frac{\vec{A} \cdot d\vec{l}}{\Delta S} = \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z}$$

8

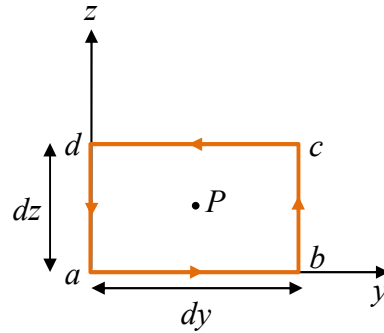
## Curl of a Vector

$$\lim_{\Delta S \rightarrow 0} \oint_L \frac{\vec{A} \cdot d\vec{l}}{\Delta S} = \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z}$$

$$(\text{curl})_x = \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z}$$

$$(\text{curl})_y = \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x}$$

$$(\text{curl})_z = \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y}$$



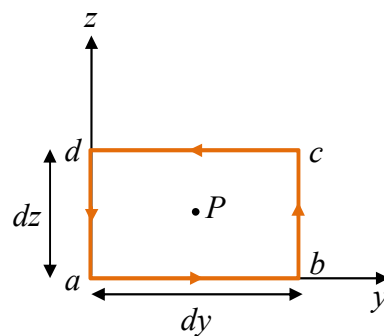
$$\nabla \times \vec{A} = \left[ \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right] \hat{a}_x + \left[ \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right] \hat{a}_y + \left[ \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right] \hat{a}_z$$

9

## Curl of a Vector

**In Cartesian coordinates**

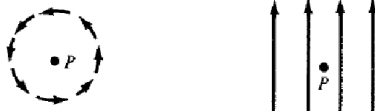
$$\nabla \times \vec{A} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix}$$



10

## Physical Significance

How much the vector curls around a point!



11

## Cylindrical Coordinates

$$\nabla \times \vec{A} = \frac{1}{\rho} \begin{vmatrix} \hat{a}_\rho & \rho \hat{a}_\phi & \hat{a}_z \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ A_\rho & \rho A_\phi & A_z \end{vmatrix}$$

$$\nabla \times \vec{A} = \left[ \frac{1}{\rho} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right] \hat{a}_\rho + \left[ \frac{\partial A_\rho}{\partial z} - \frac{\partial A_z}{\partial \rho} \right] \hat{a}_\phi + \frac{1}{\rho} \left[ \frac{\partial(\rho A_\phi)}{\partial \rho} - \frac{\partial A_\rho}{\partial \phi} \right] \hat{a}_z$$

12

## Spherical Coordinates

$$\nabla \times \vec{A} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{a}_r & r \hat{a}_\theta & \hat{a}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_r & r A_\theta & r \sin \theta A_\phi \end{vmatrix}$$

$$\nabla \times \vec{A} = \frac{1}{r^2 \sin \theta} \left[ \frac{\partial(A_\phi \sin \theta)}{\partial \theta} - \frac{\partial A_\theta}{\partial \phi} \right] \hat{a}_r + \frac{1}{r} \left[ \frac{1}{\sin \theta} \frac{\partial A_r}{\partial \phi} - \frac{\partial(r A_\phi)}{\partial r} \right] \hat{a}_\theta + \frac{1}{r} \left[ \frac{\partial(r A_\theta)}{\partial r} - \frac{\partial A_r}{\partial \theta} \right] \hat{a}_\phi$$

13

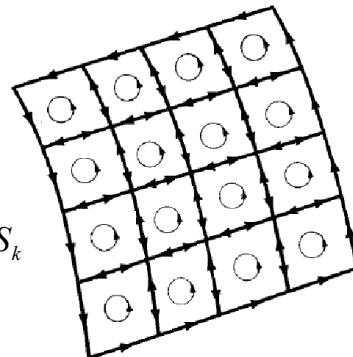
## Stokes Theorem

The circulation of a vector field  $\vec{A}$  around a (closed) path  $L$  is equal to the surface integral of the curl of  $\vec{A}$  over the open surface  $S$  bounded by  $L$  provided that  $\vec{A}$  and  $\nabla \times \vec{A}$  are continuous on  $S$ .

$$\oint_L \vec{A} \cdot d\vec{l} = \int_S (\nabla \times \vec{A}) \cdot d\vec{S}$$

**Proof:**

$$\begin{aligned} \int_L \vec{A} \cdot d\vec{l} &= \sum_k \oint_{L_k} \vec{A} \cdot d\vec{l} = \sum_k \frac{\oint_{L_k} \vec{A} \cdot d\vec{l}}{\Delta S_k} \Delta S_k \\ &= \int_S (\nabla \times \vec{A}) \cdot d\vec{S} \end{aligned}$$



14

## *Laplacian of a Scalar*

The Laplacian of a scalar field  $V$  is the divergence of the gradient of  $V$ .

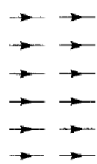
$$\text{Laplacian } V = \nabla \cdot \nabla V = \nabla^2 V$$

$$= \left[ \frac{\partial}{\partial x} \hat{a}_x + \frac{\partial}{\partial y} \hat{a}_y + \frac{\partial}{\partial z} \hat{a}_z \right] \cdot \left[ \frac{\partial V}{\partial x} \hat{a}_x + \frac{\partial V}{\partial y} \hat{a}_y + \frac{\partial V}{\partial z} \hat{a}_z \right]$$

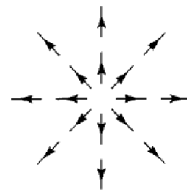
$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2}$$

15

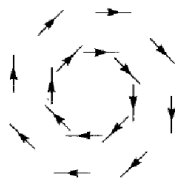
## *Divergence and Curl of Vector Fields*



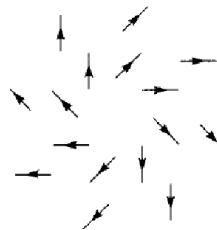
$$\nabla \cdot \vec{A} = ?, \nabla \times \vec{A} = ?$$



$$\nabla \cdot \vec{A} = ?, \nabla \times \vec{A} = ?$$



$$\nabla \cdot \vec{A} = ?, \nabla \times \vec{A} = ?$$



$$\nabla \cdot \vec{A} = ?, \nabla \times \vec{A} = ?$$

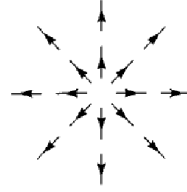
16



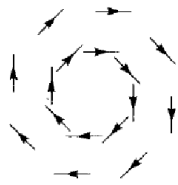
## *Divergence and Curl of Vector Fields*



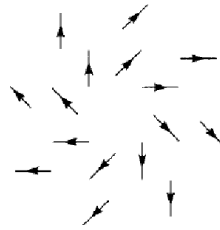
$$\nabla \cdot \vec{A} = 0, \nabla \times \vec{A} = 0$$



$$\nabla \cdot \vec{A} \neq 0, \nabla \times \vec{A} = 0$$



$$\nabla \cdot \vec{A} = 0, \nabla \times \vec{A} \neq 0$$



$$\nabla \cdot \vec{A} \neq 0, \nabla \times \vec{A} \neq 0$$

17